

SET

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**M.Sc. MATHEMATICS
SECOND SEMESTER
MECHANICS & TENSOR
MSM – 204**

[USE OMR FOR OBJECTIVE PART]

Duration: 1.30hrs

Full Marks: 35

Time: 10 min.

Marks: 10

[Objective]

Choose the correct answer from the following:

$1 \times 10 = 10$

1. In the expression $a_i x^j$, i is called
 - a. Real suffix
 - b. Dummy suffix
 - c. Kronecker delta
 - d. None of the above
2. The statement "The minimum number of coordinate required to explain the state of a system completely" are called
 - a. Generalized coordinates
 - b. Cartesian coordinates
 - c. Polar coordinates
 - d. Spherical coordinates
3. Hamiltonian Principle for a monogenic system can be stated as the motion of a system from time t_1 to time t_2 is such that the line integral

a. $I = \int_{t_1}^{t_2} L dt$, has a value

b. $I = \int_{t_1}^{t_2} Edt$ has a stationary value

c. $I = \int_{t_1}^{t_2} Edt$ has a value

d. $I = \int_{t_1}^{t_2} L dt$ has a stationary value

4. $A'^{\dagger} \partial_j = ?$
 - a. A^j
 - b. $A'^{\dagger} A_j$
 - c. A^i
 - d. A'^{\dagger}_j

5. In case of a simple pendulum, the Lagrangian

a. $L = \frac{1}{2} m^2 l^2 \dot{\theta}^2 + mgl(1 - \cos \theta)$

b. $L = \frac{1}{2} m^2 l^2 \dot{\theta}^2 - mgl(1 + \cos \theta)$

c. $L = \frac{1}{2} m^2 l^2 \dot{\theta}^2 - mgl(1 - \cos \theta)$

d. $L = \frac{1}{2} m^2 l^2 \dot{\theta}^2 + mgl(1 + \cos \theta)$

6. For the metric $ds^2 = 5(dx^1)^2 + 3(dx^2)^2 + 4(dx^3)^2 - 6dx^1dx^2 + 4dx^2dx^3$, $g = ?$
- a. -4
 - b. 4
 - c. 2
 - d. -2
7. $[ij, k] + [jk, i] = ?$
- a. $\partial_j g_{ik}$
 - b. $\partial_i g_{jk}$
 - c. $\partial_k g_{ij}$
 - d. $\partial_j g_{kk}$
8. Velocity expression in plane polar coordinate system
- a. $\vec{V} = \dot{r}\hat{e} + r\dot{\theta}\hat{\theta}$
 - b. $\vec{V} = \dot{r}\hat{e} - r\dot{\theta}\hat{\theta}$
 - c. $\vec{V} = \dot{r}\hat{e} + r\dot{\theta}\hat{\theta}$
 - d. $\vec{V} = \dot{r}\hat{e} - r\dot{\theta}\hat{\theta}$
9. For a rotating rigid body $KE = ?$
- a. $\frac{1}{2}Iw^2$
 - b. $\frac{1}{2}mv^2$
 - c. $\frac{1}{2}mw^2$
 - d. none of above
10. $\frac{dJ}{dt} = ?$
- a. $\sum \vec{P}_j \times \vec{F}_i$
 - b. $\vec{P}_i \times \vec{F}$
 - c. $\sum \vec{P}_j \times \vec{F}_j$
 - d. $\sum \vec{P}_i \times \vec{F}_i$

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(Descriptive)

Time : 1 hr. 15 mins.

Marks : 25

[Answer question no.1 & any two (2) from the rest]

1. Prove That Fundamental metric tensor g_{ij} is a covariant second rank tensor 5
2. Find the velocity and acceleration of a moving particle in Cylindrical coordinate system 4+6=10
3. State and Prove Euler-Lagrange Equation from D'Alembert's Principle 2+8=10
4. What is the definition of contraction? If a mixed tensor, contravariant of rank p and covariant of rank q , we equate a contravariant and covariant index and sum with regard to that index ,then the resulting set of N^{p+q-2} sums is a mixed tensor ,contravariant of rank $p-1$ and covariant of rank $q-1$ 1+9=10
5. What do you mean by Impulse and Impulsive force?State and Proof Carnot's Theorem 2+2+6
=10

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